

既知状態量の共分散が与えられる場合の推定

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$$\mathbf{x} = \begin{pmatrix} \mathbf{x}_{est} \\ \mathbf{x}_{known} \end{pmatrix}, \quad \mathbf{P} = \begin{pmatrix} \mathbf{P}_{est} & \mathbf{0} \\ \mathbf{0} & \mathbf{P}_{known} \end{pmatrix}$$

$$\mathbf{G} = \left. \frac{\partial \mathbf{g}}{\partial \mathbf{x}} \right|_{\mathbf{x}_{est} = \hat{\mathbf{x}}_{est}^-, \mathbf{x}_{known} = \mathbf{x}_{known}} = \begin{pmatrix} \frac{\partial \mathbf{g}}{\partial \mathbf{x}_{est}} & \frac{\partial \mathbf{g}}{\partial \mathbf{x}_{known}} \end{pmatrix} = (\mathbf{G}_{est}, \mathbf{G}_{known})$$

$$\begin{aligned} \mathbf{K} &= \mathbf{P}^- \mathbf{G}^T (\mathbf{G} \mathbf{P}^- \mathbf{G}^T + \mathbf{R})^{-1} \\ &= \begin{pmatrix} \mathbf{P}_{est}^- & \mathbf{0} \\ \mathbf{0} & \mathbf{P}_{known} \end{pmatrix} \begin{pmatrix} \mathbf{G}_{est}^T \\ \mathbf{G}_{known}^T \end{pmatrix} \left( \begin{pmatrix} \mathbf{G}_{est} & \mathbf{G}_{known} \end{pmatrix} \begin{pmatrix} \mathbf{P}_{est}^- & \mathbf{0} \\ \mathbf{0} & \mathbf{P}_{known} \end{pmatrix} \begin{pmatrix} \mathbf{G}_{est}^T \\ \mathbf{G}_{known}^T \end{pmatrix} + \mathbf{R} \right)^{-1} \\ &= \begin{pmatrix} \mathbf{P}_{est}^- \mathbf{G}_{est}^T \\ \mathbf{P}_{known} \mathbf{G}_{known}^T \end{pmatrix} \left( \mathbf{G}_{est} \mathbf{P}_{est}^- \mathbf{G}_{est}^T + \mathbf{G}_{known} \mathbf{P}_{known} \mathbf{G}_{known}^T + \mathbf{R} \right)^{-1} \end{aligned}$$

$$\mathbf{K}_{est} = \mathbf{P}_{est}^- \mathbf{G}_{est}^T \left( \mathbf{G}_{est} \mathbf{P}_{est}^- \mathbf{G}_{est}^T + \underline{\mathbf{G}_{known} \mathbf{P}_{known} \mathbf{G}_{known}^T} + \mathbf{R} \right)^{-1}$$

$$\hat{\mathbf{x}}_{est}^+ = \hat{\mathbf{x}}_{est}^- + \mathbf{K}_{est} (\mathbf{z} - \mathbf{g}(\hat{\mathbf{x}}_{est}^-, \mathbf{x}_{known}))$$

$$\mathbf{P}_{est}^+ = \mathbf{P}_{est}^- - \mathbf{K}_{est} \mathbf{G}_{est} \mathbf{P}_{est}^-$$