

International Symposium on GNSS 2015 Kyoto

17B1-12

QZSS-1 Precise Orbit Determination by MADOCA

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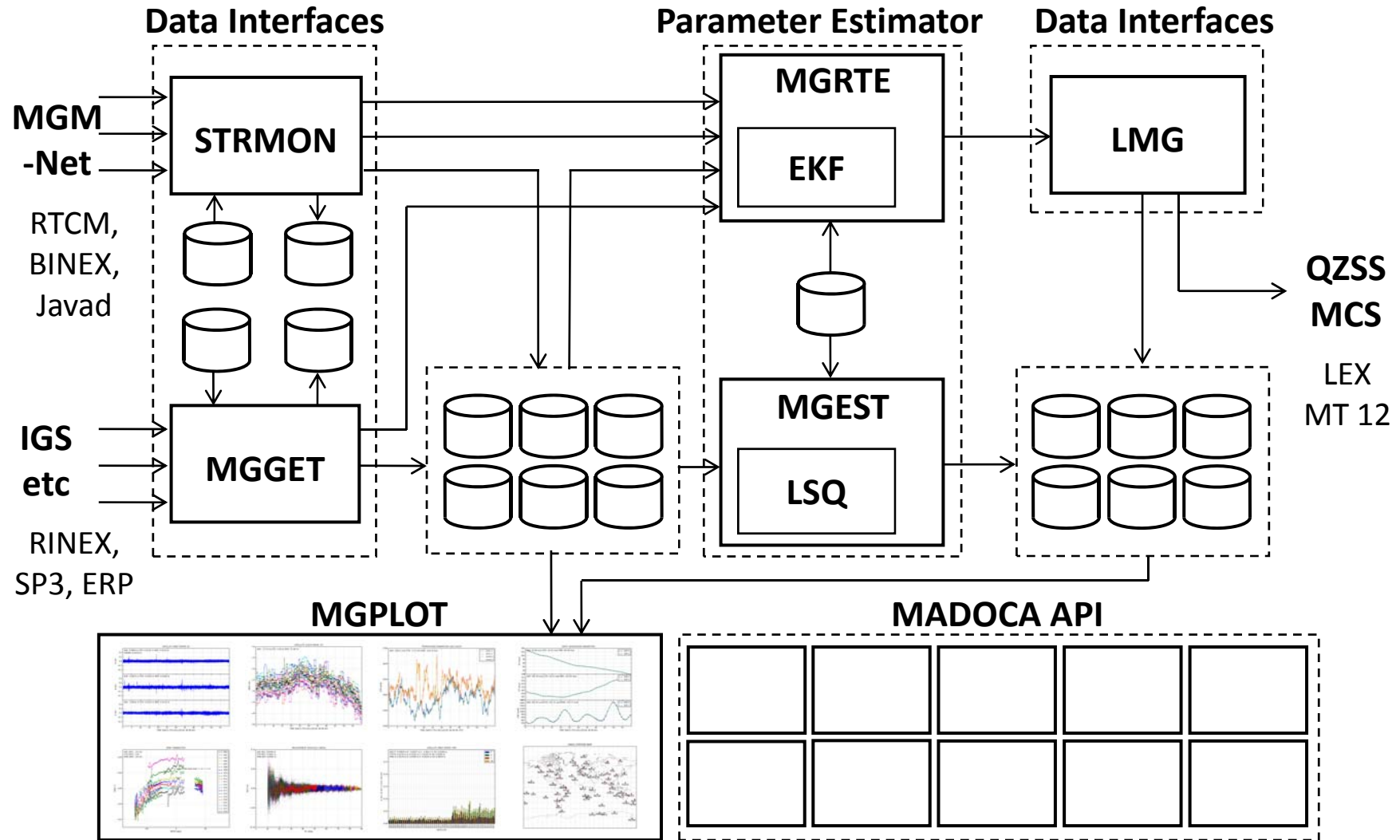
MADOCA and QZSS-1 Overview

MADOCA

Multi-GNSS Advanced Demonstration tool for Orbit and Clock Analysis

- **Developed by JAXA from scratch (2011/6~)**
- **Originally for real-time PPP service via QZSS LEX**
Many (potential) applications over global area
- **Satellite orbit and clock determination for multi-GNSS constellation**
GPS, GLONASS, QZSS, Galileo and BeiDou
- **Both of batch and real-time processing**

MADOCA Architecture

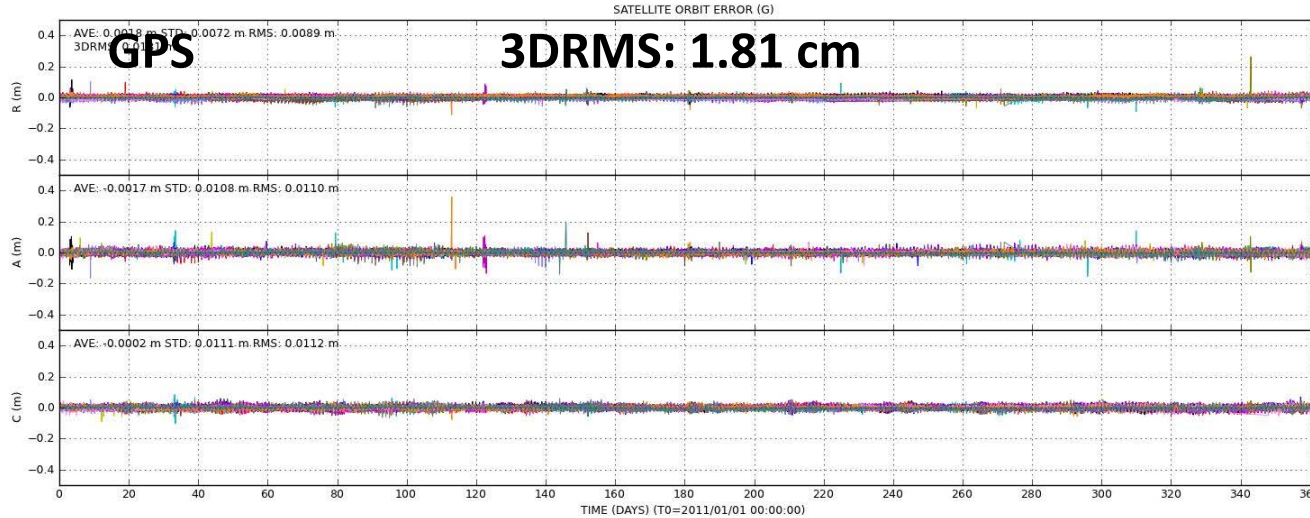


GPS/GLO Orbit Accuracy

Radial

Along-Track

Cross-Track



RMS
0.89 cm

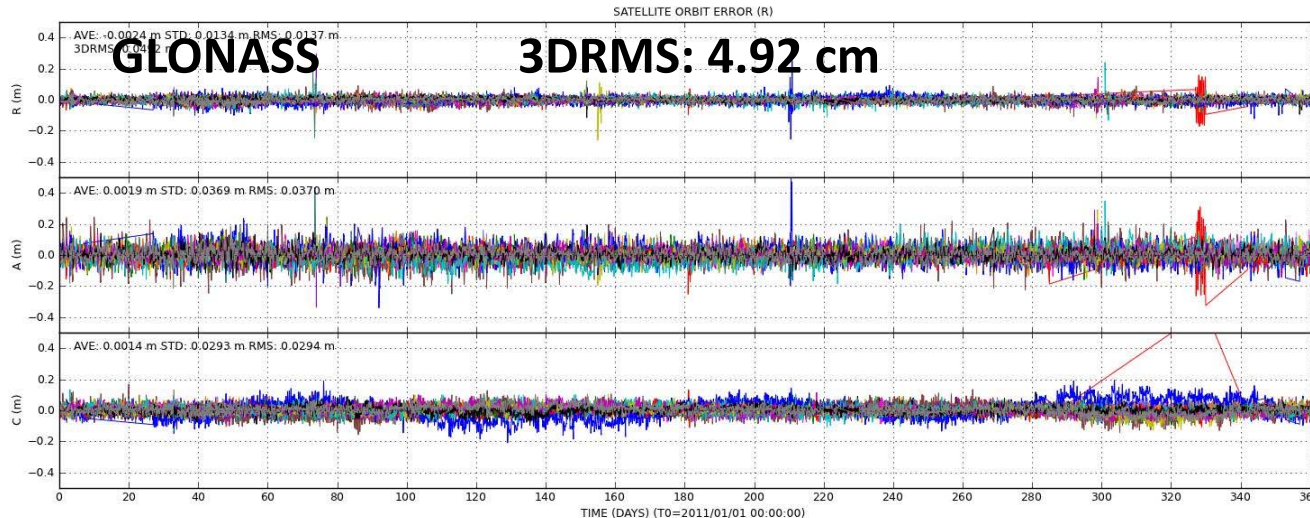
1.10 cm

1.12 cm

Radial

Along-Track

Cross-Track



1.37 cm

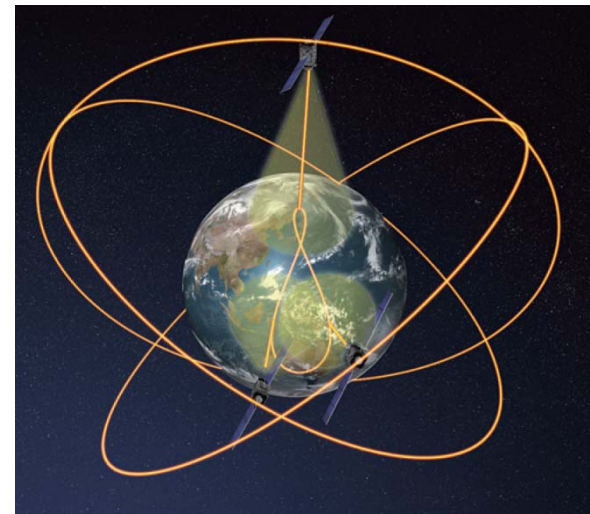
3.70 cm

2.94 cm

2011/1/1 - 12/31 (365 days), by MADOCA 0.3.0, wrt IGS Final

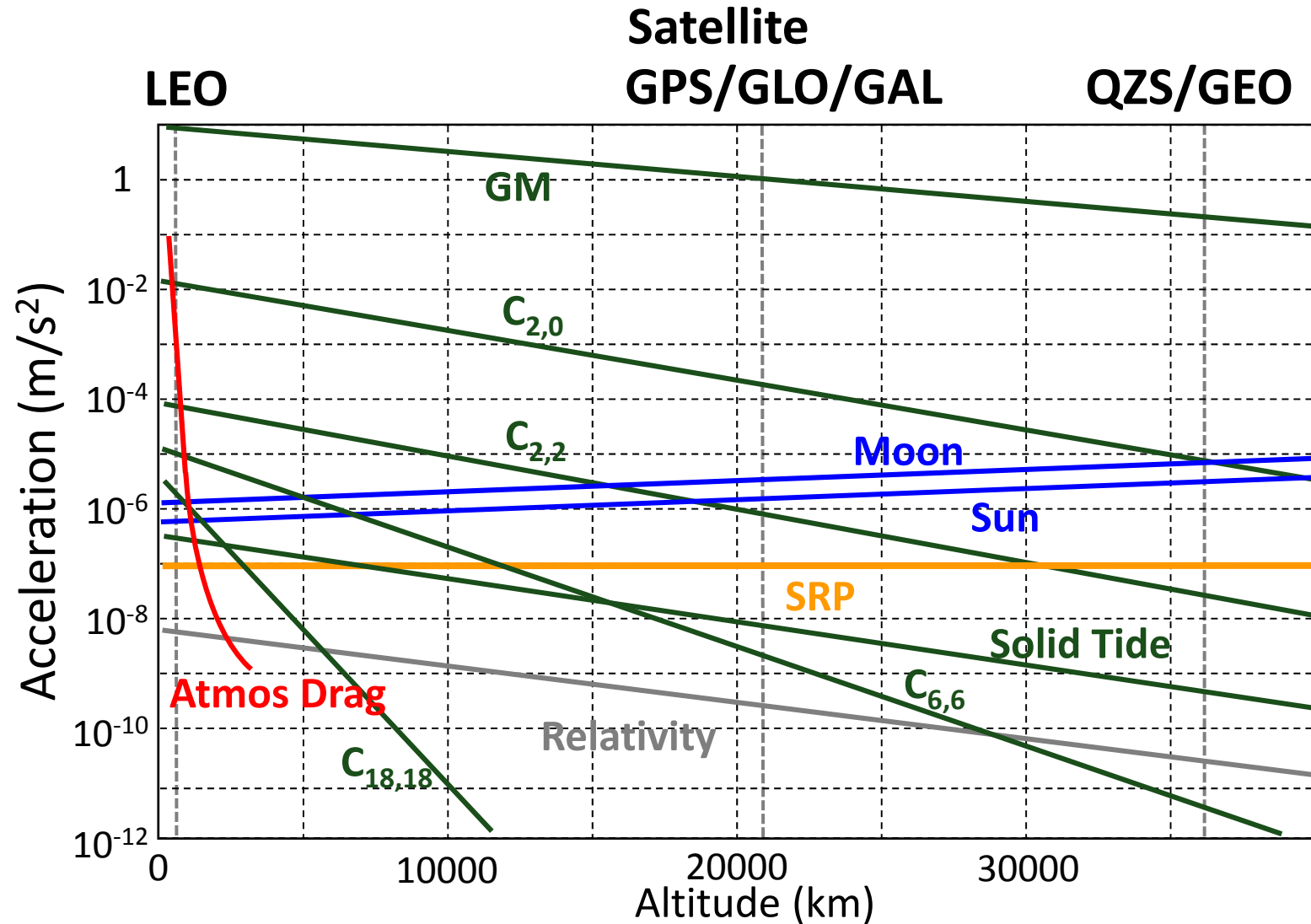
QZSS-1 "Michibiki"

- **The first Regional Navigation Satellite in Japan**
- **Launch:**
September 11, 2010 by H2A-18
- **Orbit: IGSO**
($A=42164$ km, $e=0.075$, $i=43$ deg, $\omega=270$ deg)
- **Navigation Signals:**
L1C/A, L1C, L1-SAIF, L2C, L5, LEX
- **Developed and operated by JAXA**



QZSS-1 Orbit Determination

Force Models (1/2)



Force Models (2/2)

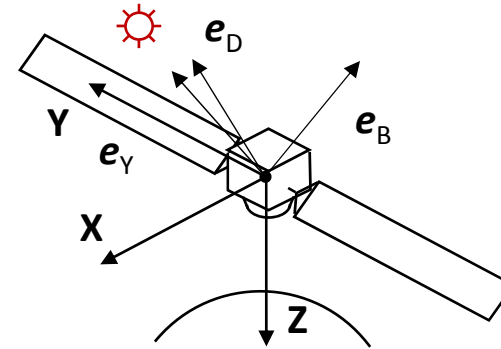
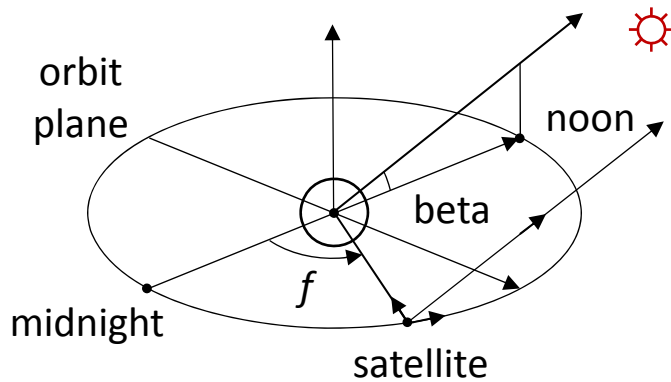
$$\mathbf{a}(t, \mathbf{r}, \mathbf{v}, \mathbf{p}) = \mathbf{a}_{geop} + \mathbf{a}_{body} + \mathbf{a}_{srp} + \mathbf{a}_{drag} + \mathbf{a}_{emp} + \mathbf{a}_{thru} + \mathbf{a}_{rel}$$

- **Geopotential**
 - EGM96 or EGM2008 up to 150 order/degree
 - Rate, solid earth tide, pole tide corrections by IERS 2010
 - Ocean tide corrections by IERS 2010 and FES2004
- **Third-Body Potentials**
 - Moon, Sun, Jupiter and Venus (point of mass)
 - Planetary ephemeris by JPL DE405/421
- **SRP, Atmospheric Drag, Empirical Accel., Thruster Accel. and General Relativity**

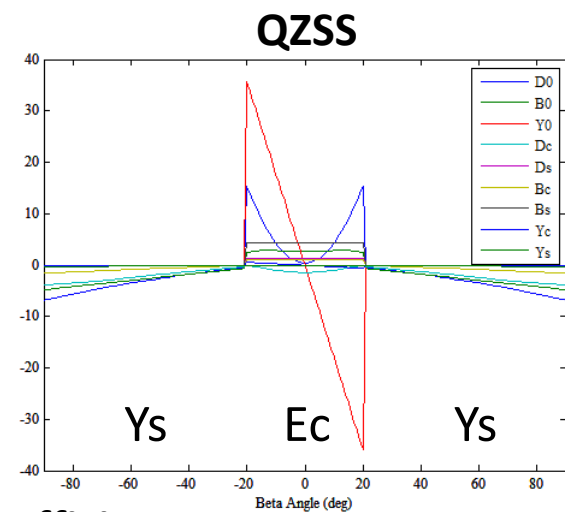
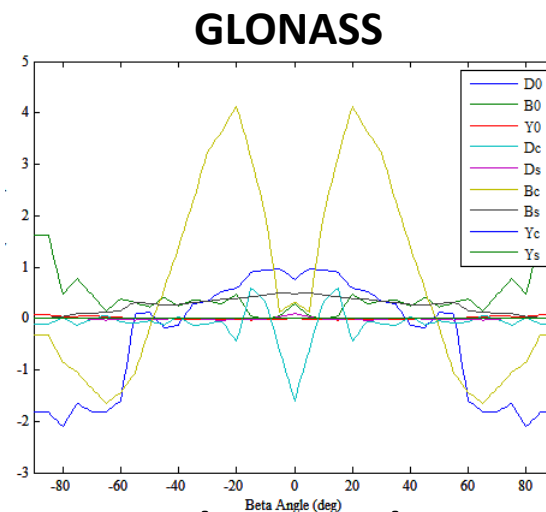
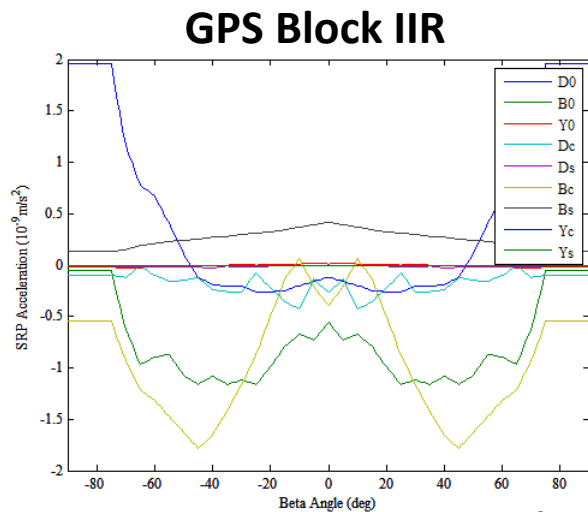
Parameter Adjustment

	Batch	Real-Time
Algorithm	Iterated Weighted LSQ	Dual-Cycle-EKF
Estimated Parameters	Orbit, SRP, Drag, Emp-Acc, Thru-Acc, Sat/Rcv Clock, Position, ZTD/Grad, Amb, EOP, Geocenter, Rcv Bias	
Measurements	ZD (zero-diff.) Carrier-Phase and Pseudorange	
Numerical Solver	NEQ by Cholesky Factorization	Numerical Stable EKF
Clock Estimation	Parameter Elimination in NEQ	State as White-Noise or Random-Walk
Integer Ambiguity Resolution	Network AR (Ge., 2005)	Real-Time Network AR

MDBY SRP Model (~ver.0.6.7)

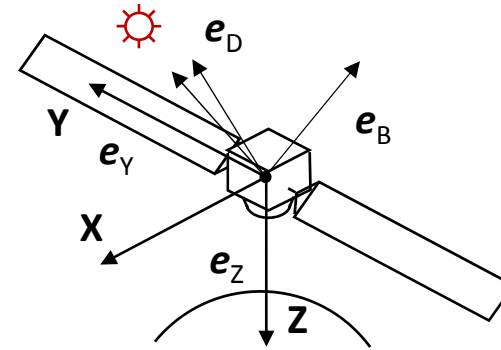
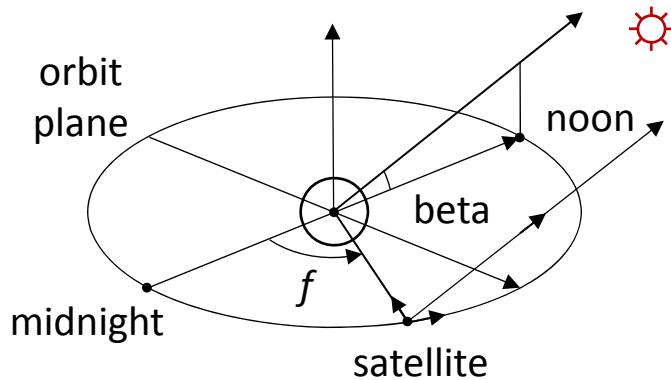


$$\mathbf{a}_{srp} = S \left((D_0 + D_C \cos f + D_S \sin f) \mathbf{e}_D + (B_0 + B_C \cos f + B_S \sin f) \mathbf{e}_B + (Y_0 + Y_C \cos f + Y_S \sin f) \mathbf{e}_Y \right) * 10^{-9} \text{ (m/s}^2\text{)}$$



Correction by Beta Angle Dependent SRP Coefficients

EDBY SRP Model (ver. 0.7.0~)



YS:

$$\mathbf{a}_{srp} = S \left((D_0 + D_C \cos f + D_S \sin f) \mathbf{e}_D + \right. \\ \left. (B_0 + B_C \cos f + B_S \sin f) \mathbf{e}_B + \right. \\ \left. (Y_0 + Y_C \cos f + Y_S \sin f) \mathbf{e}_Y + \right. \\ \left. (Z_0 + Z_C \cos f + Z_S \sin f) \mathbf{e}_Z \right) * 10^{-9} \text{ (m/s}^2\text{)}$$

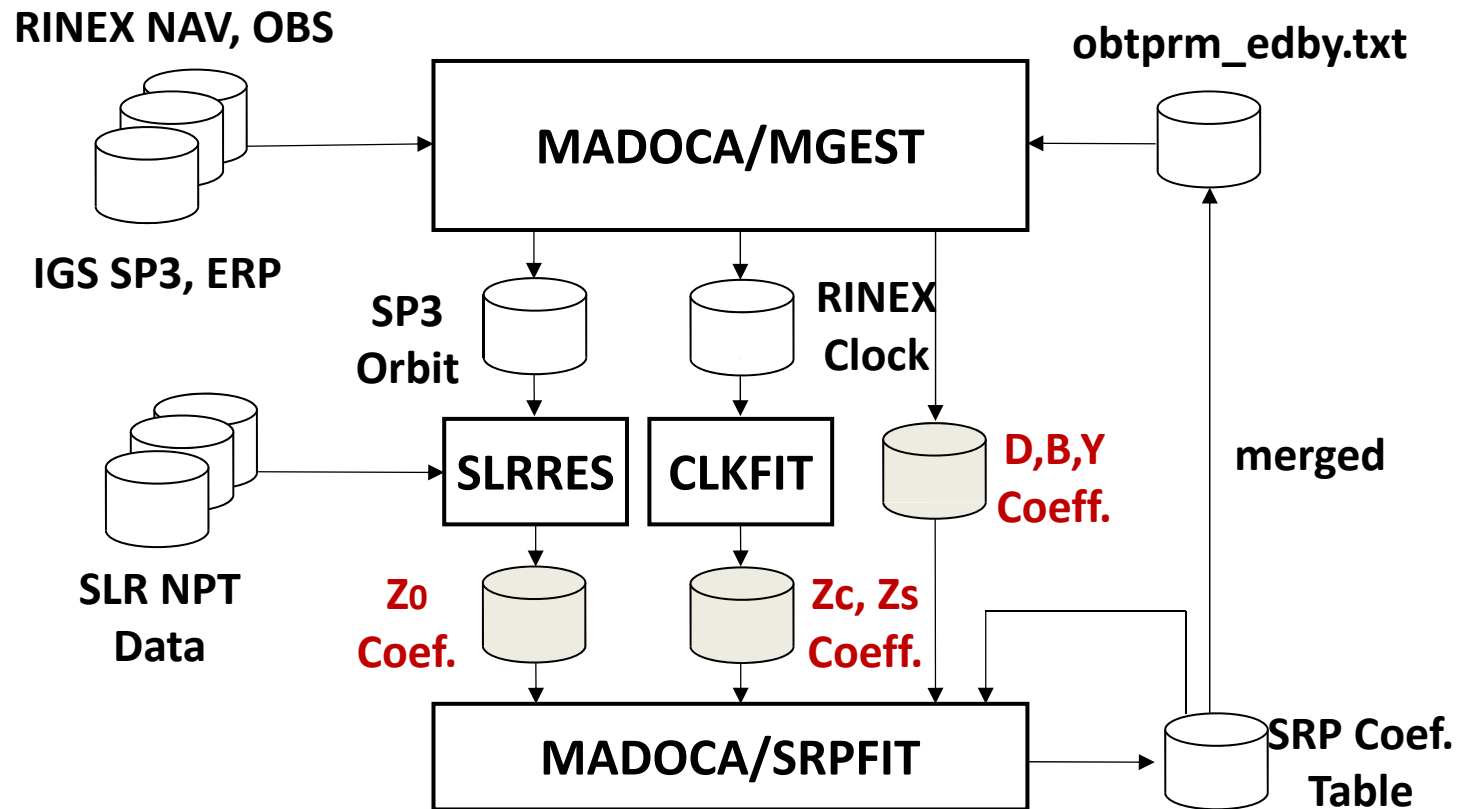
EC:

$$\mathbf{a}_{srp} = S \left((D_0 + D_C \cos f + D_S \sin f + \right. \\ \left. D_{2C} \cos 2f + D_{2S} \sin 2f) \mathbf{e}_D + B_0 \mathbf{e}_B + \right. \\ \left. (Y_0 + Y_C \cos f + Y_S \sin f) \mathbf{e}_Y + \right. \\ \left. (Z_0 + Z_C \cos f + Z_S \sin f) \mathbf{e}_Z \right) * 10^{-9} \text{ (m/s}^2\text{)}$$

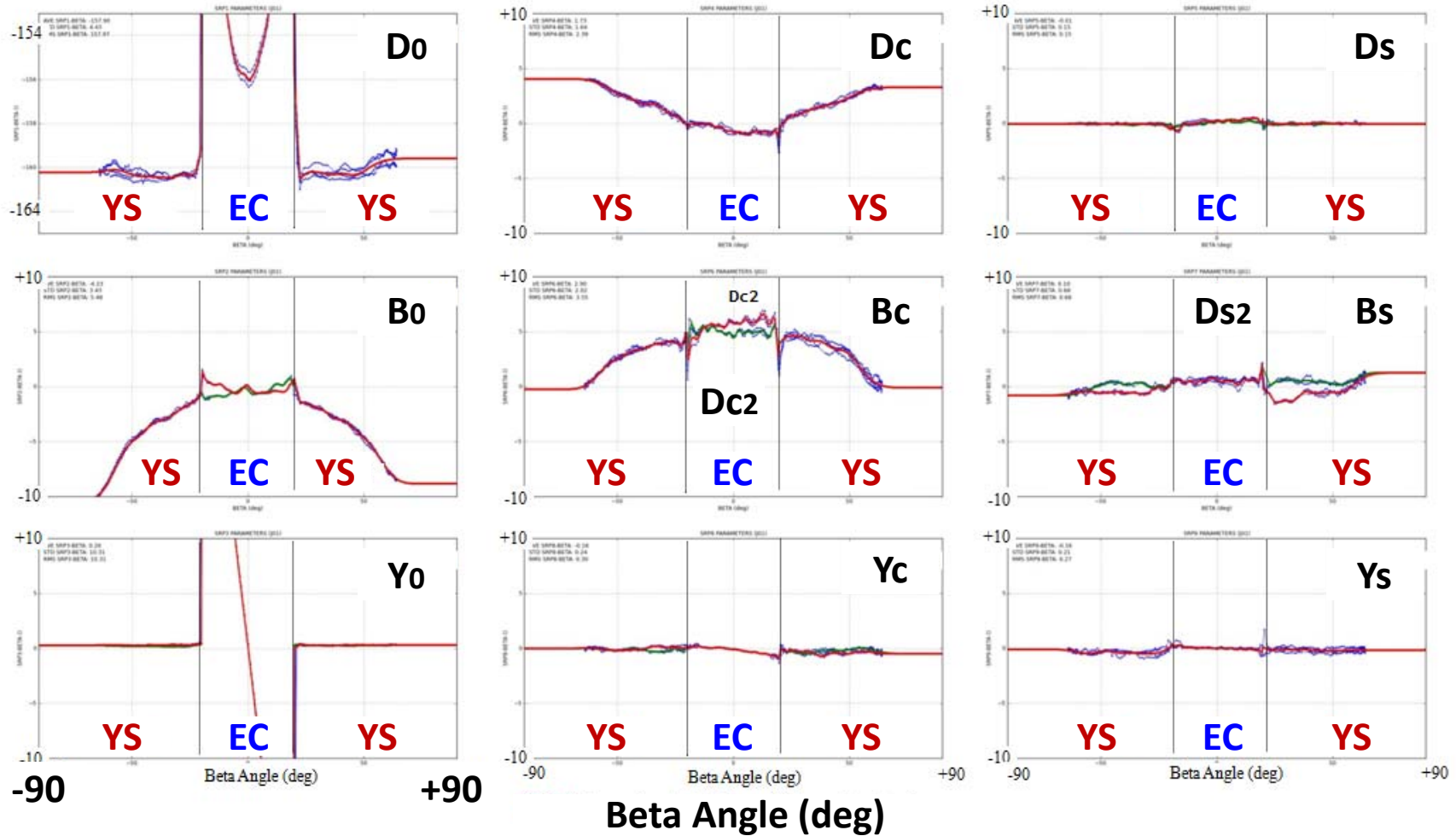
$$(S = F_{Shadow} * AU^2 / |r - r_{sun}|^2)$$

Determination of SRP Coeff.

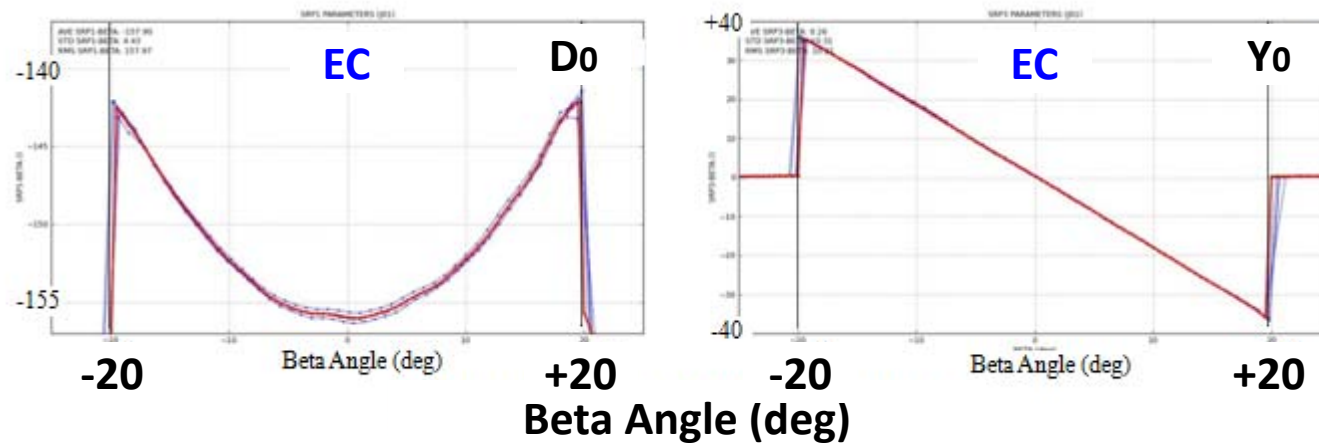
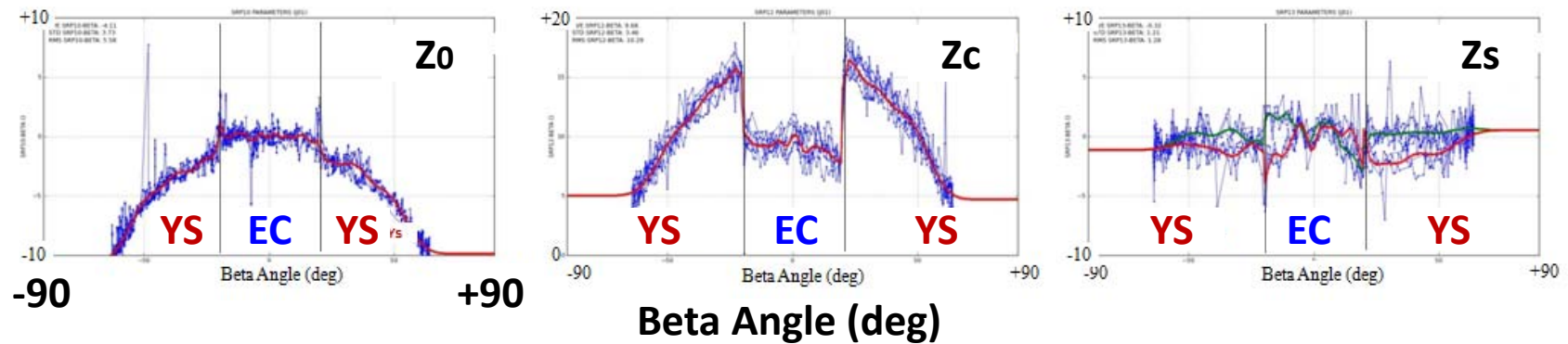
- With 23 month (2013/1 - 2014/11) MGEX/SLR Data
- Several Iterations by AWS Environment



EDBY SRP Coefficients (1/2)

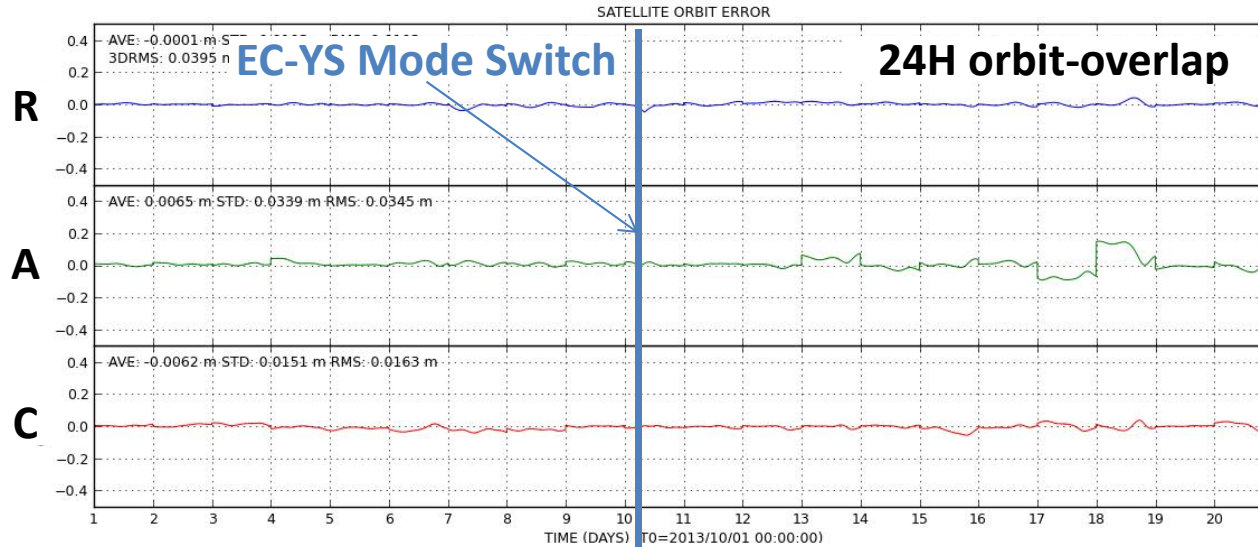


EDBY SRP Coefficients (2/2)

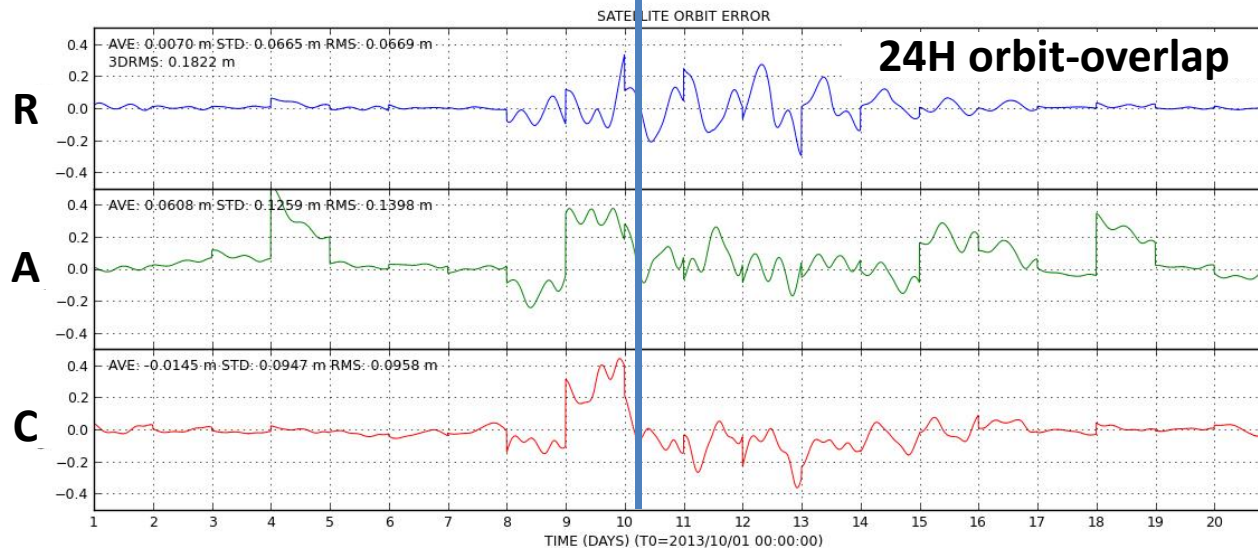


Delta-V for EC-YS Mode Switch

With
Delta-V
Estimation



Without
Delta-V
Estimation



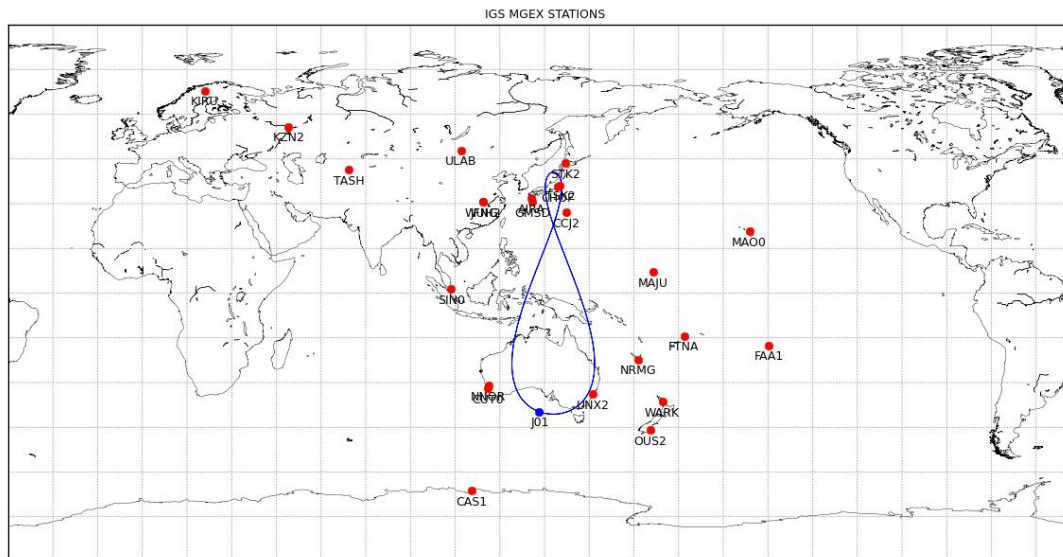
QZSS-1 Orbit Evaluation

Estimation Strategy

- **By MADOCA Batch Estimator (MGEST)**
- **Estimation Arc:**
24H+48H+24H (every 24 H)
- **OBS data:**
24 MGEX Stations RINEX Data (300 s)
- **Fixed Parameters:**
GPS Orbit (IGS Final), EOP (IGS Final) and Station Position
(Estimated by PPP by GPS only)
- **Estimated Parameters:**
QZS Orbit, QZS/GPS Clock, ZTD and Gradient, Ambiguity,
GPS-QZS Receiver Bias

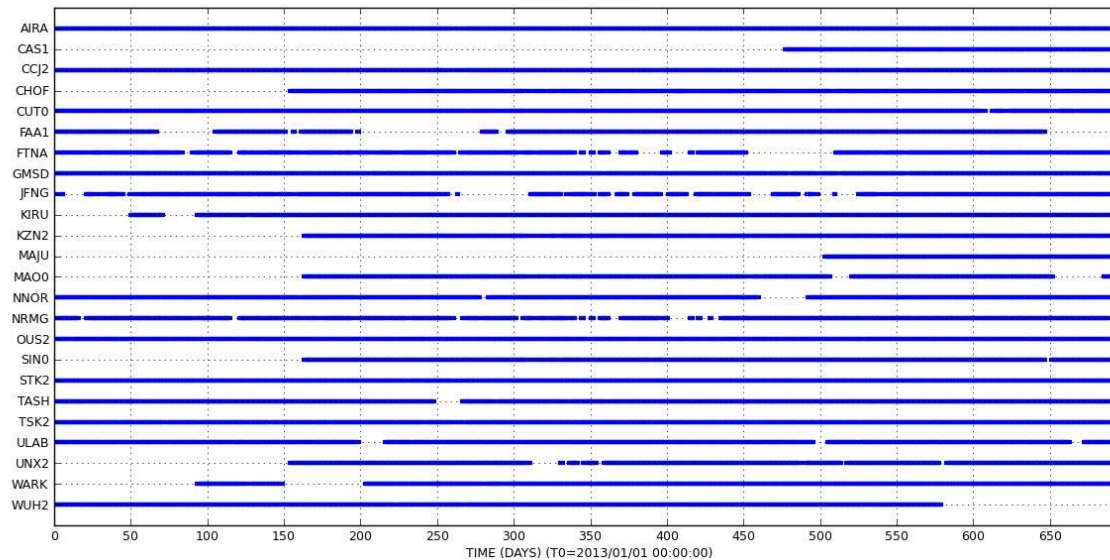
MGEX Stations

**MGEX
24 Station
Positions**



AIRA CAS1 CCJ2
 CHOF CUT0 FAA1
 FTNA GMSD JFNG
 KIRU KZN2 MAJU
 MAO0 NNOR NRMG
 OUS2 SINO STK2
 TASH TSK2 ULAB
 UNX2 WARK WUH2

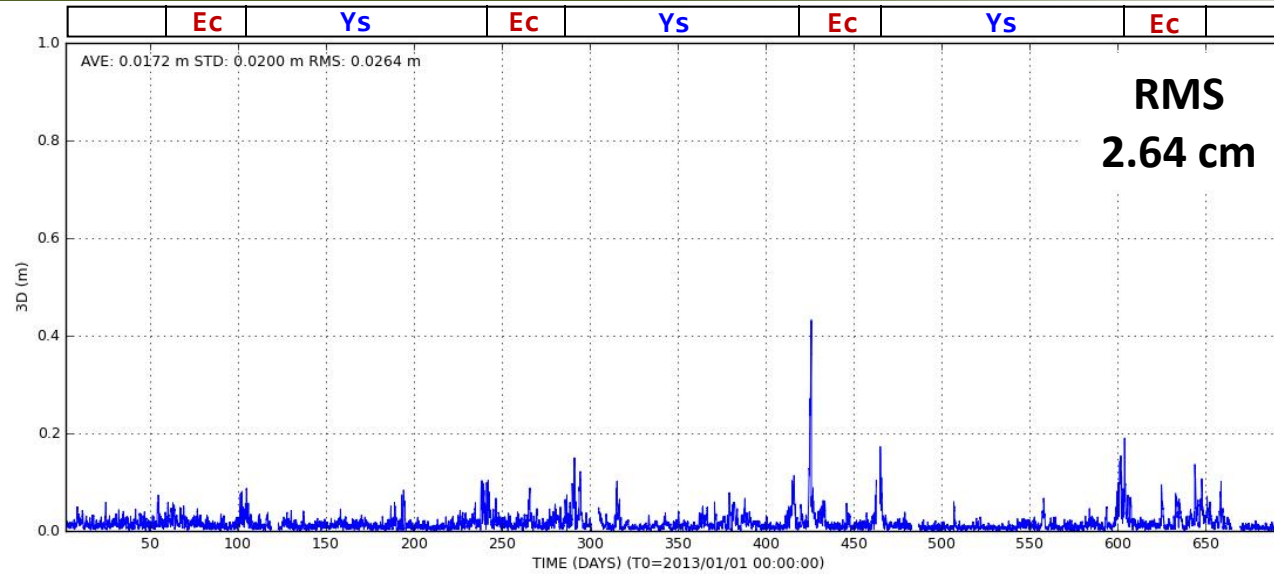
**MGEX
Data
Availability**



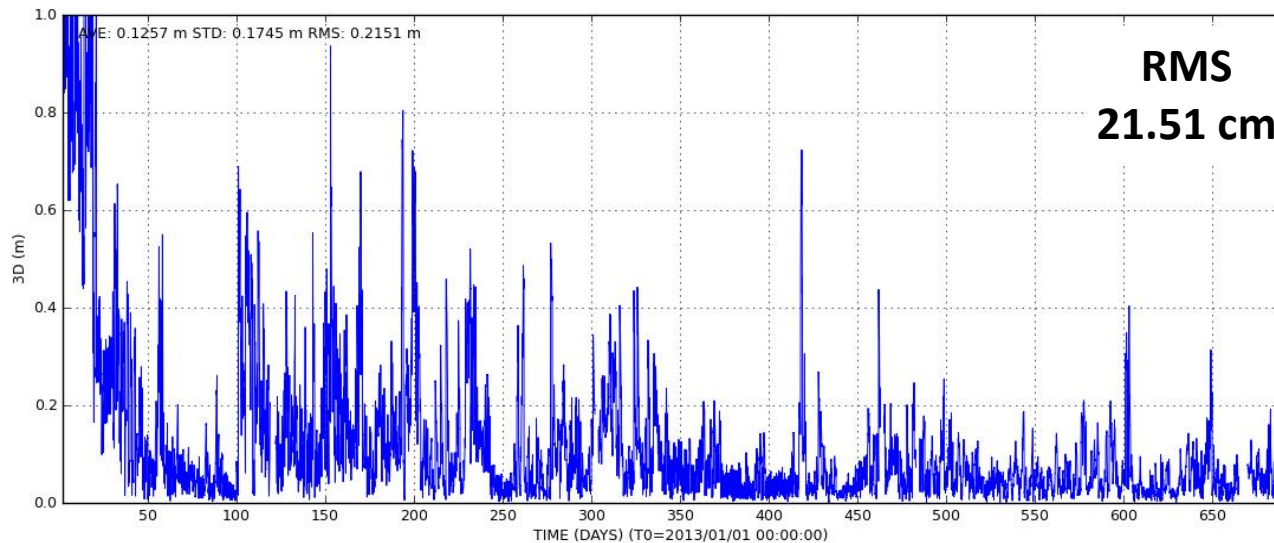
**2013/01/01
~
2014/11/30**

24H Orbit Overlap (3D)

MADOCA
0.7.0
EDBY

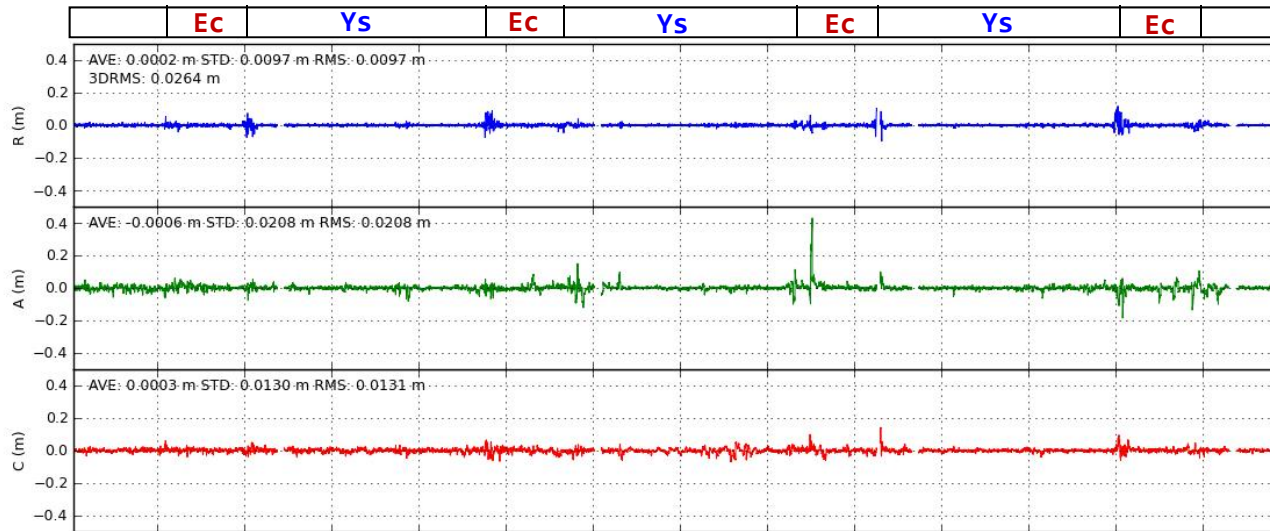


MADOCA
0.6.7
MDBY



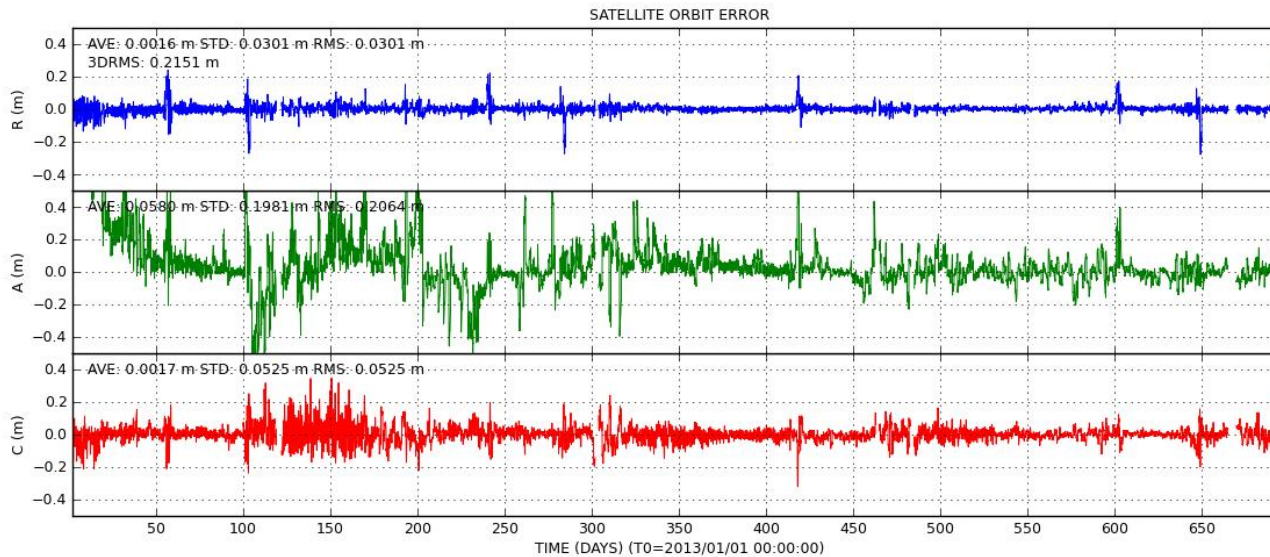
24H Orbit Overlap (RAC)

**MADOCA
0.7.0
EDBY**



RMS
R 0.97 cm
A 2.08 cm
C 1.31 cm

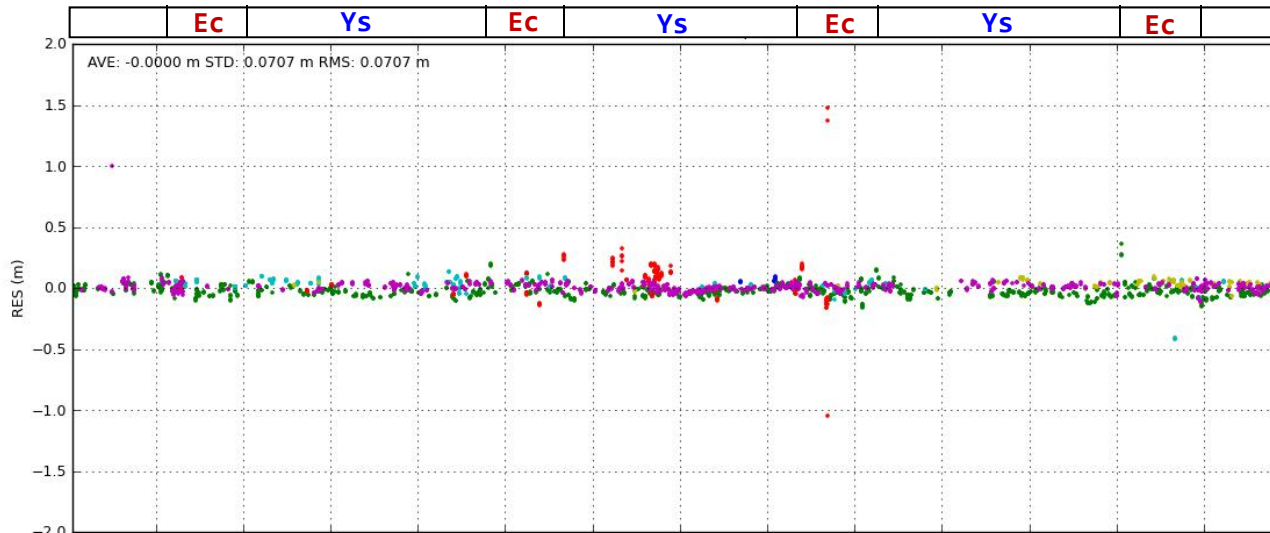
**MADOCA
0.6.7
MDBY**



RMS
R 3.01 cm
A 20.64 cm
C 5.25 cm

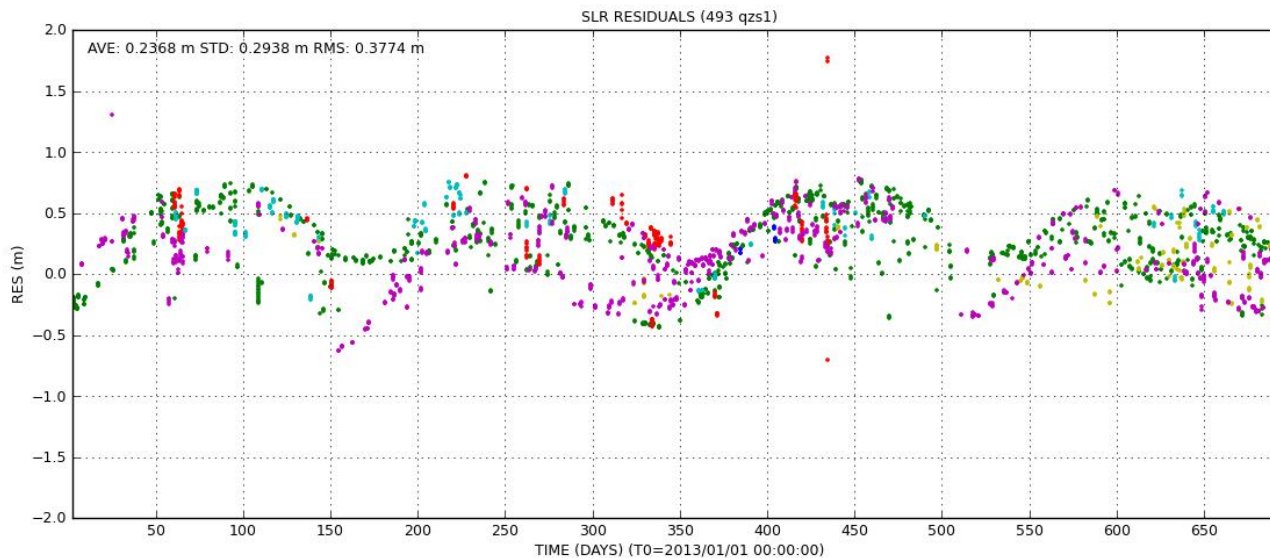
SLR Residuals (1/2)

MADOCA
0.7.0
EDBY



RMS
7.07 cm

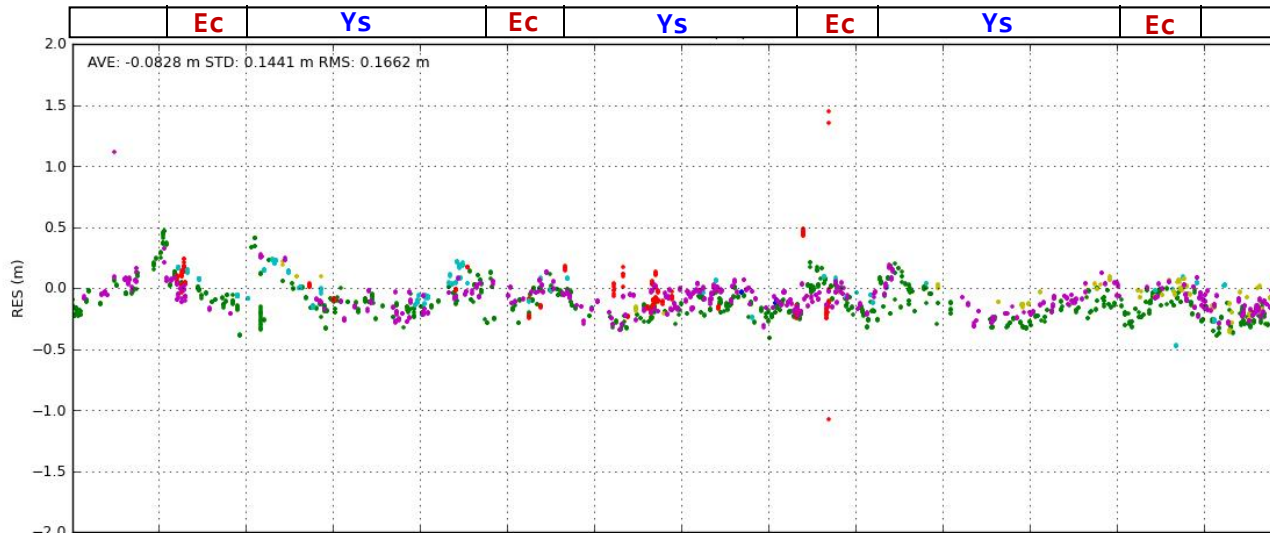
MADOCA
0.6.7
MDBY



RMS
37.74 cm

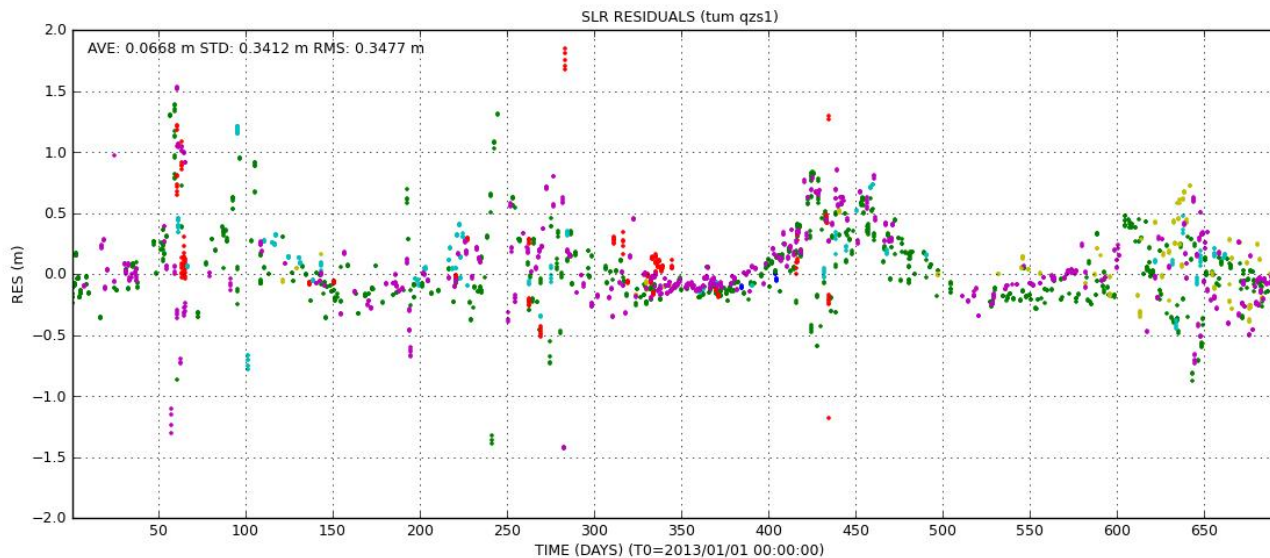
SLR Residuals (2/2)

QZS Final
Product



RMS
16.62 cm

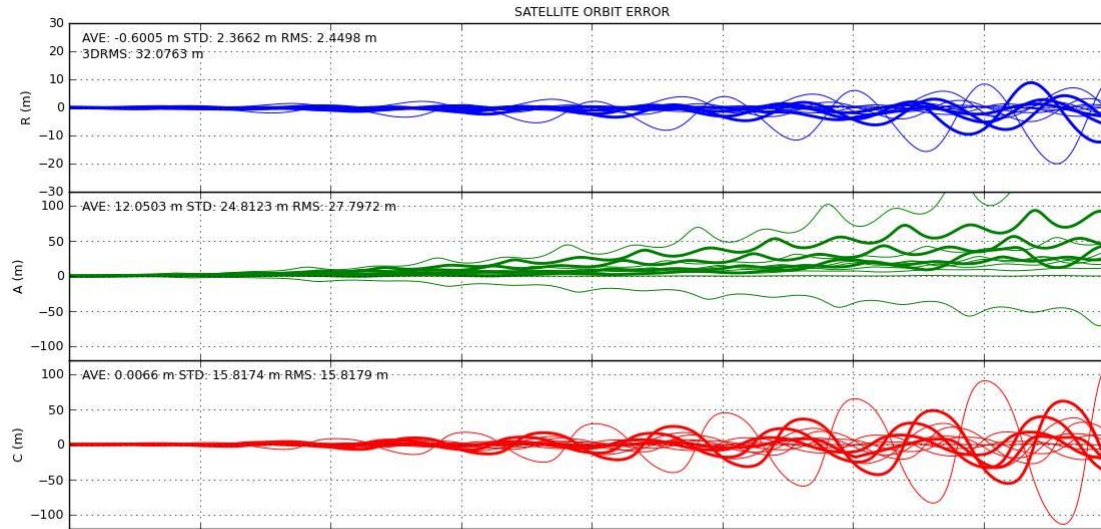
IGS
TUM
Product



RMS
34.77 cm

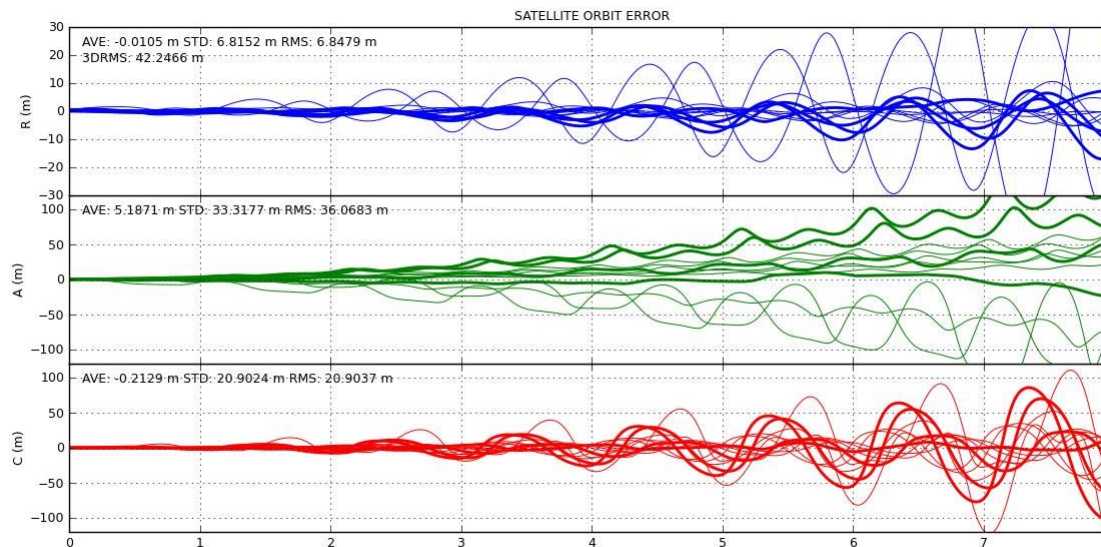
Orbit Predicted - Estimated

**MADOCA
0.7.0
EDBY**



RMS
R 2.45 m
A 27.79 m
C 15.82 m

**MADOCA
0.6.7
MDBY**



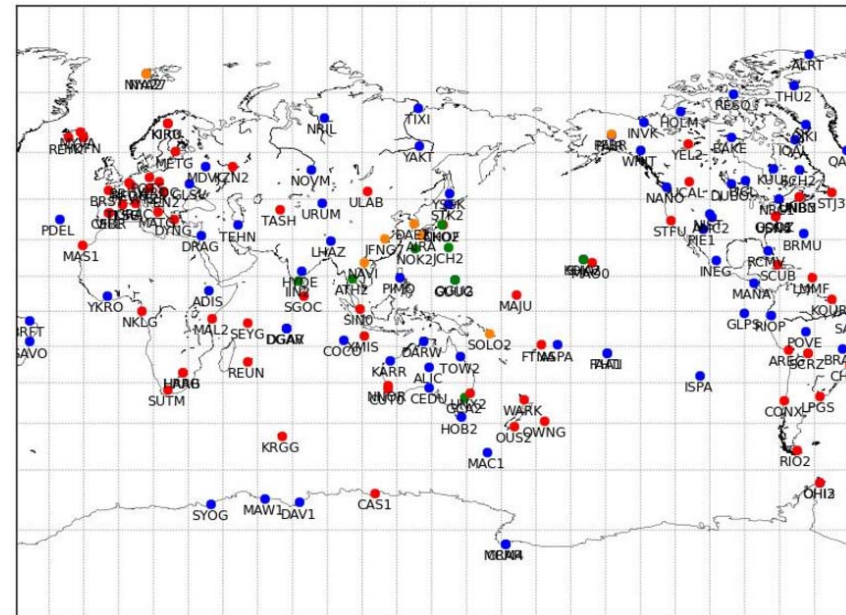
RMS
R 6.85 m
A 36.07 m
C 20.90 m

(12 cases)

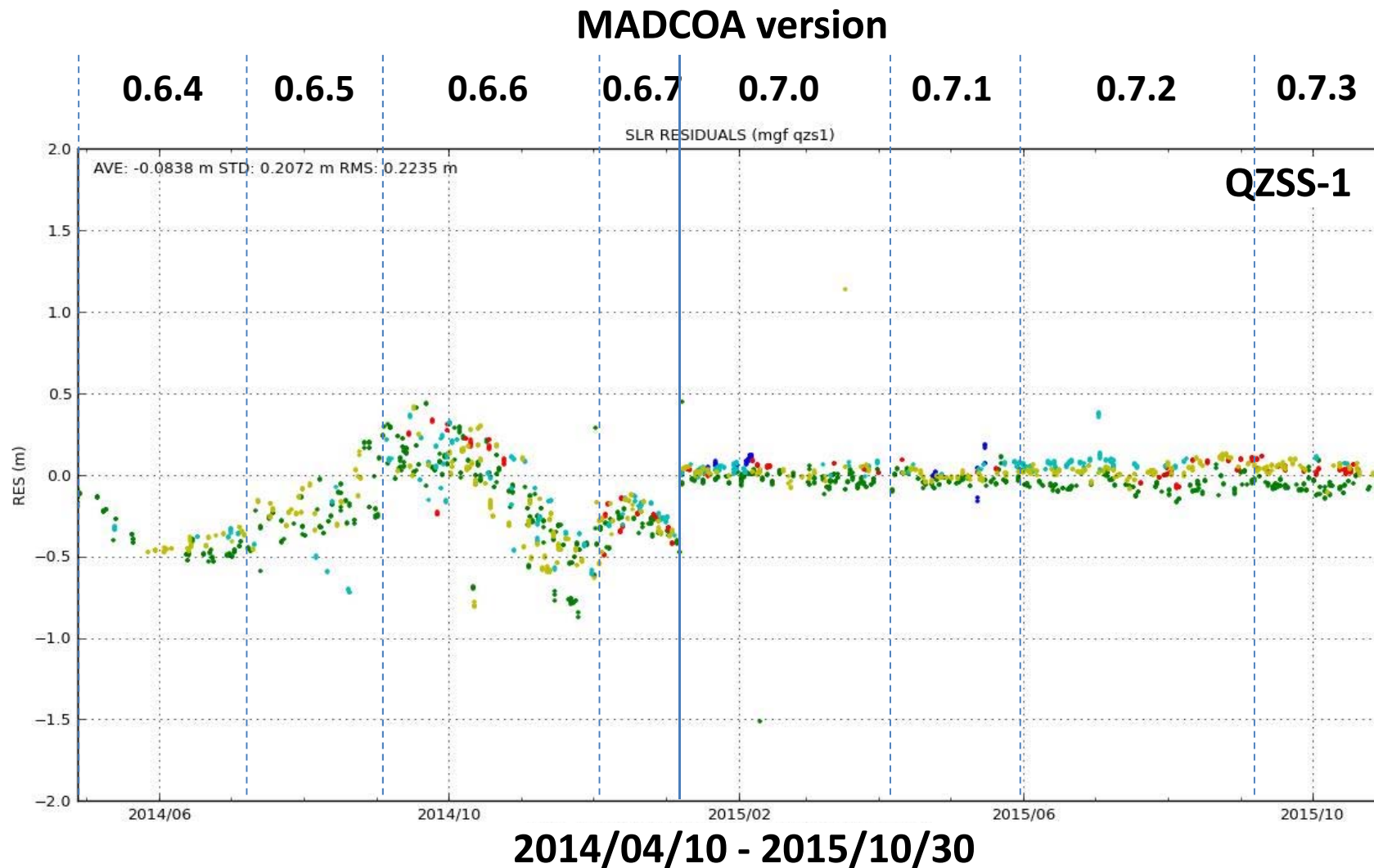
0 - 7 days

Routine Products (MGF)

- For evaluation and validation of MADOCA
- Daily (Latency: 37 - 61 H), Arc: 3H+24H+3H
- **Satellites:**
GPS/GLO/QZS (2014/4~), GAL (2015/3~),
BDS (2015/10~),
- **Products:**
SP3 Orbit, RINEX CLK (30s),
EOP, AMB, FCB (2014/8~)
- **# of Stations: 152**
IGS, MGEX, QZSS-MS,
MGM-NET



SLR Residuals of MGF



Summary

- **MADOCA and QZSS-1 Overview**
- **QZSS-1 Orbit Determination**
 - Force Models
 - Parameter Adjustment
 - SRP Model
 - Handling of EC-YS Mode Switch
- **QZSS-1 Orbit Evaluation**
 - 24H Orbit Overlap
 - SLR Residuals
 - Orbit Predicted - Estimated
 - Routine Products (MGF)